

7)

## Chap 3 , lecture 3

The finite element method for  
 elliptic equations - precise formulation

Strong formulation:

Find  $u \in C^2(\Omega)$  such that

$$-\nabla \cdot (k \nabla u) = f \quad \text{in } \Omega$$

$$u = g$$

$$k \frac{\partial u}{\partial n} = h$$

2)

We arrive at the weak form

by 1) multiplying with a test function  
and integrating over the domain

2) Use Gauss-Green's lemma

3) Use the boundary condition

[Did it in detail on the first lecture]

We arrive at the weak formulation

Given  $f \in H_0^{-1}(\Omega)$ ,  $h \in H^{-1/2}(\partial\Omega_N)$

Find  $u \in H_{g,p}^1(\Omega)$  such that

$$\int_{\Omega} (k \nabla u) \cdot \nabla v = \int_{\Omega} f v \, dx + \int_{\partial\Omega_N} h v \, ds$$

$$\forall v \in H_{0,D}^1(\Omega)$$

3)

Here

$$H_{0,D}^1(\Omega) = \left\{ u \in H^1(\Omega) \mid Tu = 0 \text{ on } \partial D_D \right\}$$

$$H_{g,D}^1(\Omega) = \left\{ u \in H^1(\Omega) \mid Tu = g \text{ on } \partial D_D \right\}$$

4)

In order to define a finite element method, let  $\mathcal{S}_h$  be a mesh consisting of a set  $E_h$  of cells. We assume that they are simplices (triangles in 2D, tetrahedrons in 3D)

Simplices fit well with standard polynomials.

~~What~~ What do I mean by that:

consider  $P_k$  the space of polynomials

5)

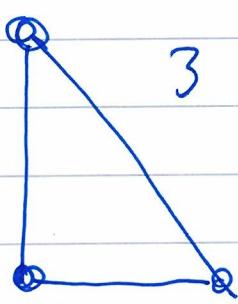
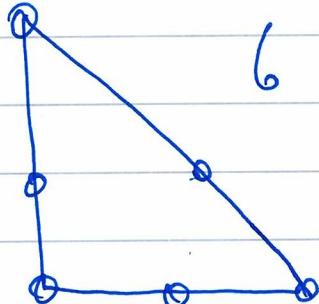
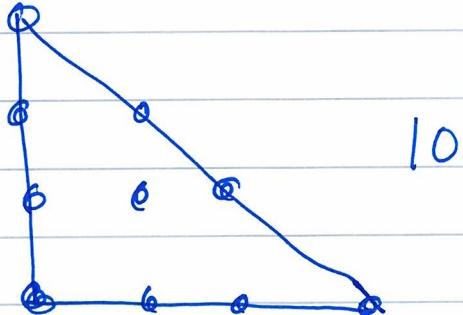
$$P_1 = \{ 1, x, y \} \quad \text{number of basis} : 3$$

$$P_2 = \{ 1, x, y, xy, x^2, y^2 \} : 6$$

$$P_3 = \{ 1, x, y, xy, x^2, y^2, x^3, x^2y, xy^2, yx^2, y^3 \} : 10$$

$$P_4 = \{ \dots, x^4, x^3y, x^2y^2, xy^3, y^4 \} : 15$$

Points :

 $P_1$  $P_2$  $P_3$ 

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6)

There are many ways  
to represent the  
polynomial space  $P_k$

- monomial / power basis
- Bessel polynomials
- Jacobi polynomials
- Lagrange polynomials.

Lagrange is very useful.

The basis is set up

such that the basis

is 1 in one of

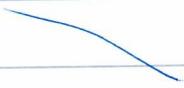
the points shown and zero  
elsewhere.

7)

hence, the basis functions

are set up such that

$$N_i(x_j) = \delta_{ij}$$



3. 2)

8)

What is an elliptic partial differential equation?

The equation is strictly positive with respect to some inner product.

We need several concepts to show positivity.

- 1) lifting
- 2) Poincaré
- 3) strict positivity of  $k$ .

Poincaré's inequality

for every  $u \in H_{0,0}^1(\Omega)$  we have

$$\|u\|_{L^2(\Omega)} \leq C \|\nabla u\|_{L^2(\Omega)}$$

the inequality can be motivated by a Taylor series

$$|f(x+h)| = |f(x)| + h f'(x) \max_{x \leq x^* \leq x+h} |f'(x^*)|$$

if  $f(x)$  is zero, which we

know it is at certain parts

of the boundary (~~so  $f \in H_{0,0}^1(\Omega)$~~ )

$$\Rightarrow |f(x+h)| \leq h \max_{x^*} |f'(x^*)|$$

10)

In  $H_{g,D}^1(\Omega)$  we do not know that  $u$  is 0 at the boundary as  $g$  can be anything.

Hence, we need to transform our problem to a problem with 0 at the boundary !

This is called lifting

The trick is easy, used in analysis but not typically in implementation.

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Let  $u$  solve ~~the~~ ~~the~~

(I write it on strong form for simplicity)

$$-\nabla \cdot (k \nabla u) = f \quad \text{in } \Omega$$

$$u = g \quad \text{on } \partial\Omega_D$$

$$k \frac{\partial u}{\partial n} = h \quad \text{on } \partial\Omega_N$$

Let then  $u = G + u_0$  where

$G|_{\partial\Omega_D} = g$  but can be anything  
elsewhere. Then  $u_0$  solves the problem

$$-\nabla \cdot (k \nabla u_0) = f + \nabla \cdot (k \nabla G)$$

$$u_0 = 0$$

$$k \frac{\partial u_0}{\partial n} = h - k \frac{\partial G}{\partial n}$$

(12)

Hence  $u_0$  solves a problem

with homogenous boundary conditions  
on part of the boundary.

The positivity of  $k$ .

We need that for every  $x \in \mathbb{R}$

$$k_0 \leq k(x) \leq k_1 \quad \forall x \in \mathbb{R}$$

13)

### 3.3 An error estimate

#### Galerkin orthogonality

Consider the numerical error

$$e_h = u - u_h$$

We have

$$\int_{\Omega} (k \nabla u) \cdot (\nabla v) dx = \int_{\Omega} f v dx + \int_{\partial \Omega_N} h v ds \quad 1)$$

and

$$\int_{\Omega} (k \nabla u_h) \cdot \nabla v_h dx = \int_{\Omega} f v_h dx + \int_{\partial \Omega_N} h v_h ds \quad 2)$$

(14)

since  $V_{h,g} \subset H_{g,D}^1$

we may in 1) choose  $v = V_h$

Then subtracting 2) from 1)

~~then~~ we get

$$\int_{\Omega} k \nabla u \cdot \nabla (u - u_h) \cdot v_h dx = \int_{\Omega} (f - f_h) v_h dx + \int_{\partial \Omega_N} (h - h_h) v_h ds = 0$$

Hence the error  $e_h = u - u_h$

is orthogonal to all  $v_h \in V_{h,g}$

with respect to the  $\int_{\Omega} k \nabla (\cdot) \cdot (\nabla \cdot)$  <sup>inner</sup> product

(5)



Result from the exercise

$$k_0 \int_{\Omega} (\nabla u)^2 dx \leq \int_{\Omega} (k \nabla u) \cdot \nabla u \leq k_1 \int_{\Omega} (\nabla u)^2 dx$$

Cea's lemma:

$$k_0 \int_{\Omega} (\nabla(u - u_n))^2 dx \leq$$

$$\int_{\Omega} (k \nabla(u - u_n)) \cdot \nabla(u - u_n) dx \leq$$

$$\int_{\Omega} k \nabla(u - u_n) \cdot \nabla(u - P_m u + P_m u - u_n) dx$$

$P_m u$  and  $u_n$  ~~are~~  $\in V_{g,h}$

$$= \int_{\Omega} k \nabla(u - u_n) \cdot \nabla(u - P_m u)$$

$$\leq k_1 \| \nabla(u - u_n) \| \| \nabla(u - P_m u) \|$$

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we already had a

bound on  $\|\nabla(u - P_m u)\| \leq Ch^{m-1} \|u\|_m$

$\Rightarrow$

$$\|u - P_m u\|_1 \leq Ch^{m-1} \|u\|_m$$

$\Rightarrow$

$$\|\nabla(u - u_n)\| \leq \frac{k_1}{k_0} Ch^{m-1} \|u\|_m$$

$m$  is the polynomial order  
of the element space.