

# Lecture 8

1)

Three things to discuss today :

1. inf-sup

2. boundary conditions for splitting/projection schemes with Navier-Stokes

3. Going from non-homogeneous Dirichlet conditions to homogeneous Dirichlet conditions  
→ lifting operations

2)

Invertibility of

$$BA^{-1}B^T \text{ ~~can~~ can}$$

be ensured if  $A^{-1}$  is  
invertible and  $B$  has  
full rank.

- $B$  has full rank would  
imply that  $BB^T$  is invertible.
- Notice that  $B^T B$  will  
not ~~have full~~ be invertible.

$B$  is  $m \times n$   $n \gg m$

3)

kernel of  $B^T = \emptyset$

(means that  $B^T$  has  
full rank.)

is equivalent to

$$\uparrow) \max_v (v, B^T p) > 0 \quad \forall p$$

In words, if  $B^T$  has a kernel

then I may choose a  $\tilde{p}$  in the

kernel and then  $B^T \tilde{p} = 0 \Rightarrow \max_v (v, B^T \tilde{p}) = 0$

An alternative (equivalent  
in finite dimension) is

4)

$$2) \max_v \frac{(v, B^T p)}{\|v\|} \geq \beta \|p\| \quad \forall p.$$

or

$$3) \max_v \frac{(Bv, p)}{\|v\|} \geq \beta \|p\| \quad \forall p.$$

In infinite dimension, the  
choice of norm is crucial

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The correct inf-sup condition for Stokes problem is

$$\sup_{v \in H_0^1} \frac{(\nabla \cdot v, p)}{\|v\|_1} \geq \beta \|p\|_0 \quad \forall p \in L^2_0$$

It is ~~called~~ called the inf-sup condition because it can also be written

$$\inf_{p \in L^2_0} \sup_{v \in H_0^1} \frac{(\nabla \cdot v, p)}{\|v\|_1} \geq \beta \|p\|_0$$

[ We discussed error estimates last time, hence I will not go through that now ]

We earlier discussed  
splitting / projection schemes  
for Navier-Stokes.

6)

Here, we discretized in time first

then in space. It enabled  
us to do certain tricks,

that is; the equations

were split into a series

of simpler equations,

The IPCS was

7)

$$1.) \quad u^* - s(u^*) + \frac{\Delta t \nabla p^n}{\rho} = f^{n+1}$$

$$2.) \quad -\nabla^2 \phi = -\frac{\rho}{\Delta t} \nabla \cdot u^*$$

$$3.) \quad u^{n+1} = u^* - \frac{\Delta t}{\rho} \nabla \phi$$

$$4.) \quad p^{n+1} = p^n + \phi$$

What is wrong with  
this scheme ?

# Boundary conditions ! (8)

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Notice here that

—  $u^*$  has the right Dirichlet boundary conditions (I assume)

— Also  $\phi$  is set up with homogenous Neumann conditions

$$\frac{\partial \phi}{\partial n}$$

$\Rightarrow$  Some things are then correct.



a)

$$u^{n+1} \cdot n = u^* \cdot n \quad \text{since}$$

$$\frac{\Delta t}{\rho} \nabla \phi \cdot n = 0$$

$$u^{n+1} \cdot t \neq u^* \cdot t \quad \text{since}$$

$$\frac{\Delta t}{\rho} \nabla \phi \cdot t \neq 0$$

in general.

Hence,  $u^{n+1} \cdot t$  may be <sup>quite</sup> wrong

depending on  $\nabla \phi \cdot t$

Also, notice that

$$p^{n+1} = p^n + \phi$$

If there is a time dependence

in  $p$  then  $\frac{\partial p^{n+1}}{\partial n}$  may not equal  $\frac{\partial p^n}{\partial n}$

I just illustrated an example of how things go wrong.

You can try to change

e.g. the homogenous

Neumann condition on  $\phi$

to improve. I will argue

that there is no general

solution to this problem.

$\Rightarrow$  IPCS will always be first order.

# Lifting

Very often, also in the material provided in this course, the homogenous Dirichlet problem is considered for error estimates.

The argument for this is that you can "always" reduce a non-homogenous problem to a homogenous.

Consider the problem

(2)

$$-\Delta u = f \quad \text{in } \Omega$$

$$u = g \quad \text{on } \partial\Omega$$

there are many functions  
that equal  $g$  on the  
boundary. Let us pick  
one

$$\hat{u} = g \quad \text{on } \partial\Omega$$

but takes values in the  
whole of  $\Omega$ .

Clearly then I can (13)

define  $\bar{u}$  by

$$\bar{u} = u - \hat{u}$$

$\bar{u}$  satisfy the equation

$$-\Delta \bar{u} = -\Delta u - \Delta \hat{u} = f - \Delta \hat{u} \quad \text{in } \Omega$$

$$\bar{u} = u - \hat{u} = g - g = 0 \quad \text{on } \partial\Omega.$$

14)

In other words, one  
may argue that it  
is sufficient to solve  
the problem

$$-\Delta u = f \quad \text{in } \Omega$$

$$u = 0 \quad \text{on } \partial\Omega$$

as any non-homogenous  
Dirichlet problem may be  
reduced to this.

For the most part of  
analysis you therefore see

the space  $H_0^1(\Omega)$  rather than  
 $H_g^1(\Omega)$