

Week 6

1)

Navier - Stokes

$$\frac{\partial v}{\partial t} + \boxed{v \cdot \nabla v} = -\frac{1}{\rho} \nabla p \quad \boxed{+\nu \nabla^2 v} + g$$
$$\nabla \cdot v = 0$$

On non-dimensionalized form

$$\frac{\partial v^*}{\partial t^*} + \boxed{(v^* \cdot \nabla^* v^*)} = -\nabla^* p^* \quad \boxed{+\frac{1}{Re} \nabla^{*2} u^*} + f^*$$

$$Re = \frac{v L}{\nu}$$

---

Our example is

2)

$$-\mu \Delta u + v \cdot \nabla u = f$$

↑  
diffusivity

↑  
velocity

viscosity  
if  $u$  is  
a vector

Peclet number

$$= \frac{\text{advective transport rate}}{\text{diffusive transport rate}}$$

$$= \frac{Lv}{\mu}$$

3)

Reynolds number  
or Pechlet number  
is a kind of a  
condition number,  
that is it measures  
the conditioning of  
the operator relative  
to viscous / diffusive  
transport rate

4)

Last time we

saw that

$$a(u, v) = \int_{\Omega} \mu \nabla u \cdot \nabla v +$$

$$\int_{\Omega} v \cdot \nabla u \, w$$

$$\leq (\mu + \|v\|_{\infty} C_2) \|u\|_1 \|v\|_1$$

The next question

5)

is then (in linear algebra terms)

$$x^T A x \geq \alpha \|x\|^2$$

And this is kind of cool

Assume that  $\nabla \cdot v = 0$

(which in most cases is  
ok )

$$\text{Let } c_v(u, w) = \int v \cdot \nabla u w$$

6)

We can then show

that

$$C_v(u, w) = -C_v(w, u)$$

which means that ( $w = u$ )

$$C_v(u, u) = -C_v(u, u) = 0$$

linear algebra equivalent

$$x^T C x = 0 \quad \forall x \neq 0$$

$C$  is anti-symmetric,

i.e.  $C = -C^T$ .

Example

$$C = \frac{1}{h} \begin{bmatrix} 0 & -1 & & & & & \\ 1 & 0 & & & & & \\ & 1 & -1 & & & & \\ & & 1 & 0 & & & \\ & & & 1 & -1 & & \\ & & & & 1 & 0 & -1 \\ & & & & & 1 & 0 \end{bmatrix}$$

2-order central difference

$$\frac{u_{i+1} - u_{i-1}}{2h}$$

⇒ Transport is typically  
anti-symmetric → (energy preservation)

8)

We wanted to show that

$$C_v(u, w) = -C_v(w, u)$$

||

$$\int_{\Omega} v \cdot \nabla u w = - \int_{\Omega} v \cdot \nabla w u$$

$$\begin{aligned} \nabla \cdot v &= 0 \\ - \int_{\Omega} \nabla \cdot v u w \end{aligned}$$

integration by parts

$$+ \int_{\Gamma} u w v \cdot n$$

Boundary conditions

$$\Rightarrow - \int_{\Omega} v \cdot \nabla w u = -C_v(w, u)$$



The conclusion is

that

$$\alpha = \nu$$

$$c = (\nu + \|v\|_\infty C_2)$$

The error estimate becomes :

$$\|u - u_{nl}\|_1 \leq \frac{c}{\alpha} \| \leftarrow \|$$

$$\leq \frac{(\nu + \|v\|_\infty C_2)}{\nu}$$

We saw several different estimates here earlier

$$C_2 = L$$

~~$\|v\|_\infty$  could be max or min~~

If  $\nu$  is small then this is similar to Re.

10)

Let us now consider

Stokes problem

$$-\mu \Delta u - \nabla p = f$$

$$\nabla \cdot u = 0$$

We start with ~~an~~ a linear algebra type approach.

I will derive weak forms etc next time.

We saw that for

11)

the convection diffusion problem

the approximation was

tied to the properties

$$x^T A x > 0 \quad \text{and} \quad x^T A y < \infty$$

$$\forall x$$

$$\forall x, y$$

More precisely we should ~~to~~ perhaps

say

$$x^T A x \geq \alpha \|x\| \quad \text{and} \quad x^T A y \leq C \|x\| \|y\|$$

$$\forall x$$

$$\forall x, y$$

and we saw that the choice of

norm  $\|\cdot\|$  was crucial.

The Stokes problem is  
of the form

12)

$$\begin{bmatrix} A & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ d \end{bmatrix}$$

When is this problem  
solvable, i.e. when does  
it have a unique  
solution

(with  $x, y$  bounded by  $c, d$ )

(3)

For Stokes problem,  
as will be detailed next  
time,  $A \in \mathbb{R}^{n \times n}$  and is  
invertible, ~~while~~ while

$B \in \mathbb{R}^{m \times n}$  with  $m \ll n$ .

Let us use that  $A$   
is invertible.

$$Ax + B^T y = c \quad 1) \quad 14)$$

$$Bx = d \quad 2)$$

Multiply 1) with  $A^{-1}$

$$\Rightarrow x = A^{-1}(c - B^T y) \quad 3)$$

insert 3) into 2)

$$\Rightarrow BA^{-1}(c - B^T y) = d$$

or

$$-BA^{-1}B^T y = d - BA^{-1}c$$

$BA^{-1}B^T$  is called  
the Schur complement.

15

Clearly the system

$$\begin{bmatrix} A & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ d \end{bmatrix}$$

is solvable if

$$-BA^{-1}B^T y = d - BA^{-1}c$$

is solvable

$$\text{and } x = A^{-1}(c - B^T y)$$

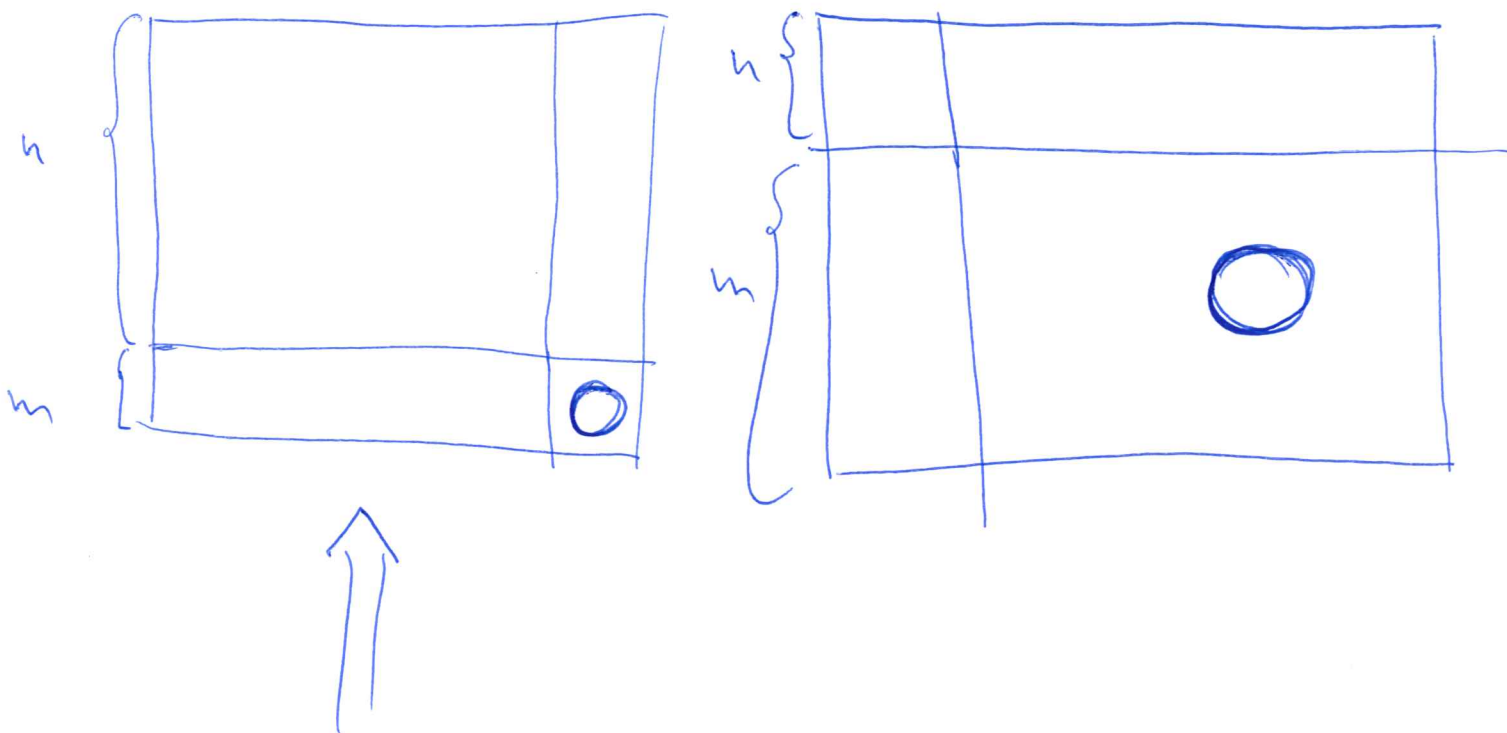
when is

16)

$BA^{-1}B$  invertible?

$A$  is  $\mathbb{R}^{n \times n}$

and  $B$  is  $\mathbb{R}^{m \times n}$ .



We are in this

situation  $n > m$ .



17)

What are

appropriate

conditions on

$B$

$Z$   
 $\rightarrow$